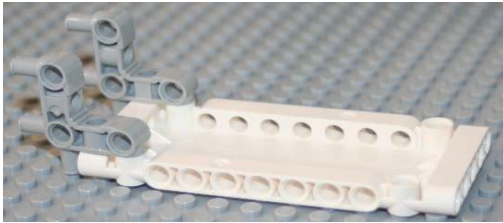


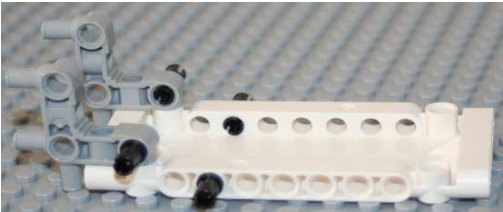

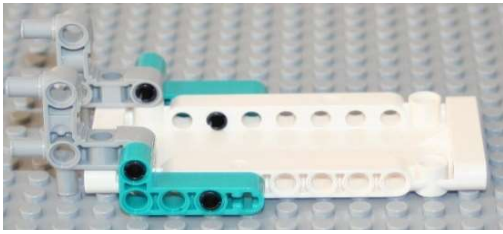

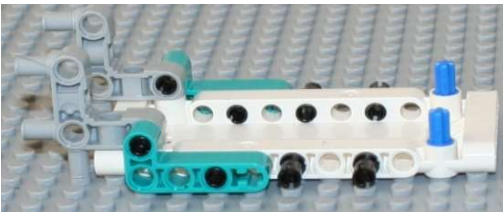


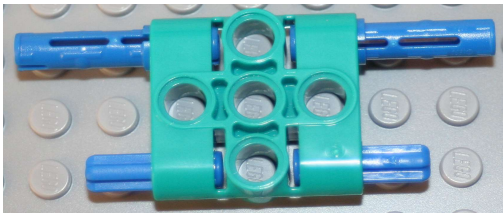



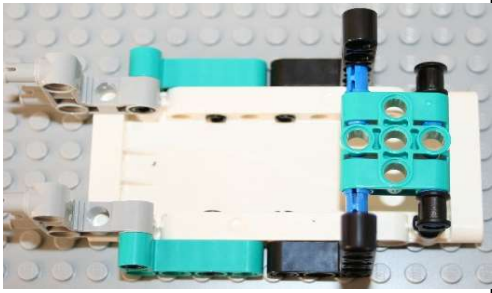

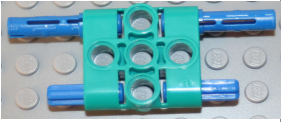

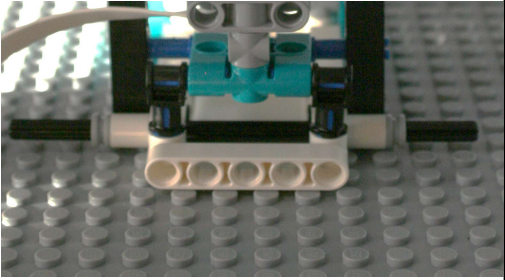



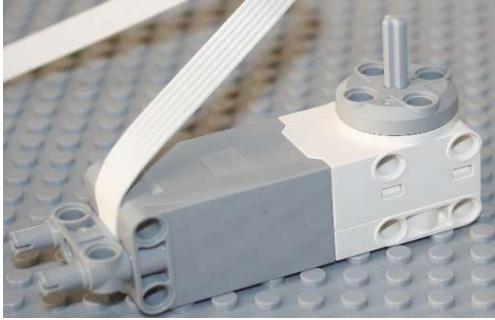
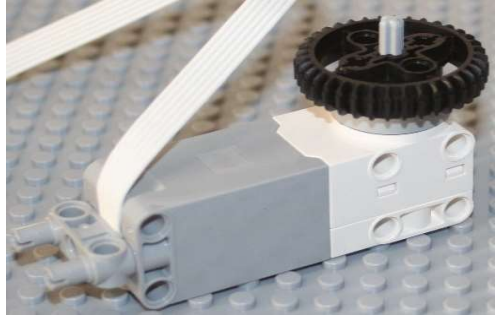
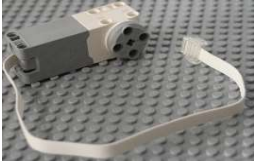



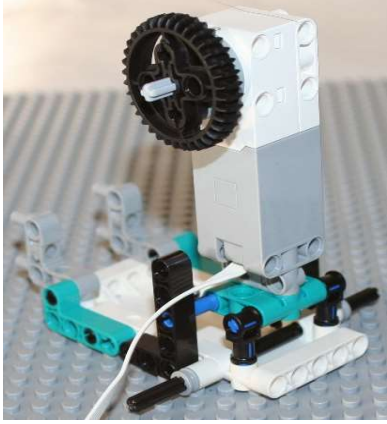
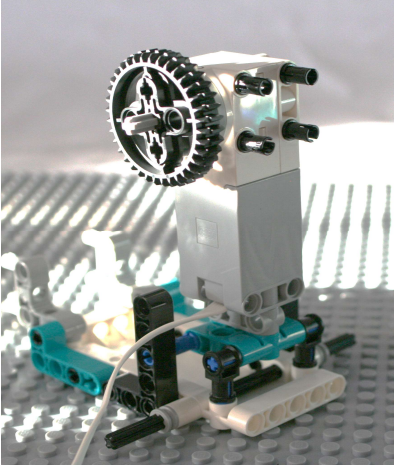

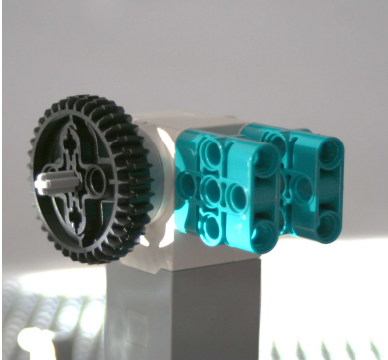

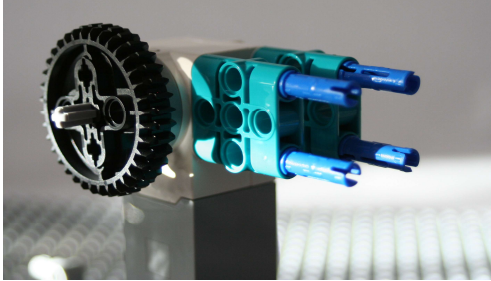

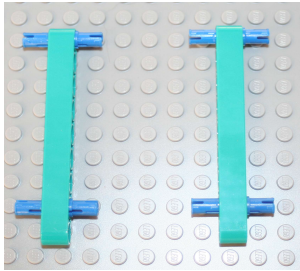


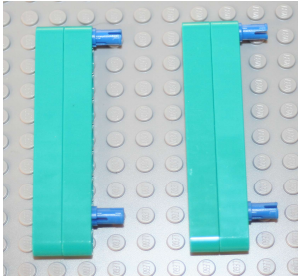

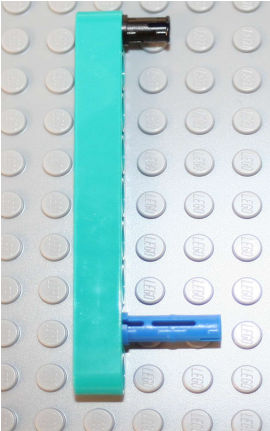



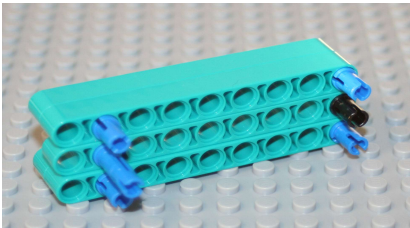
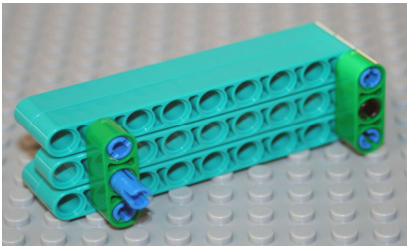





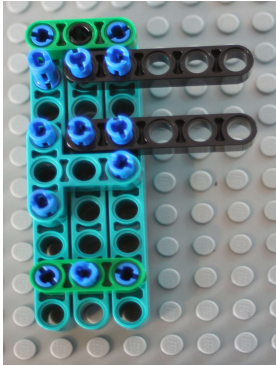


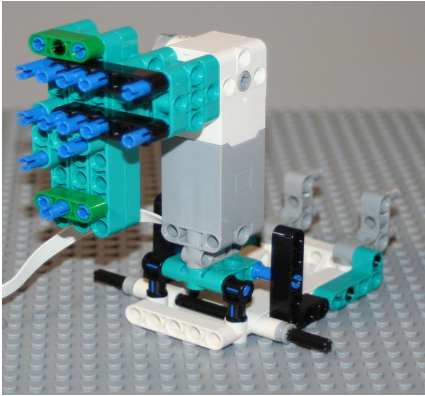
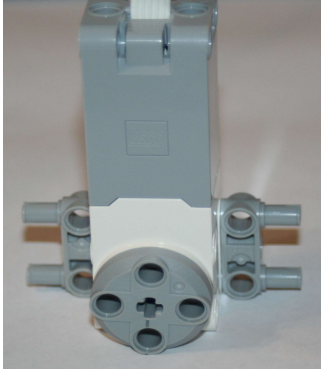
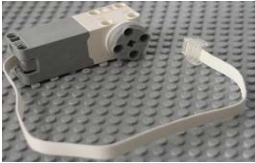

Instructions pour l'assemblage du robot

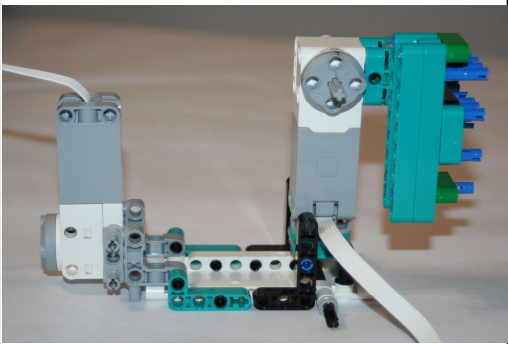
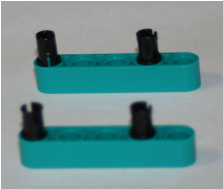


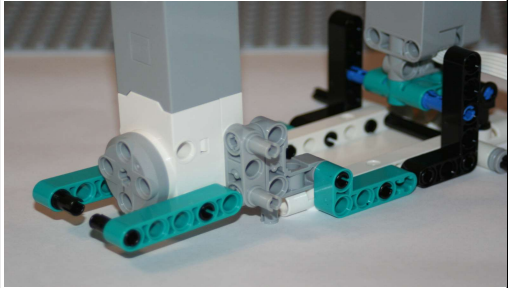

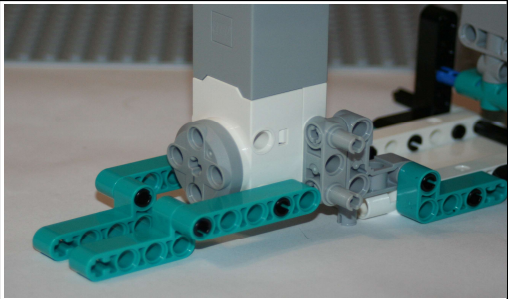

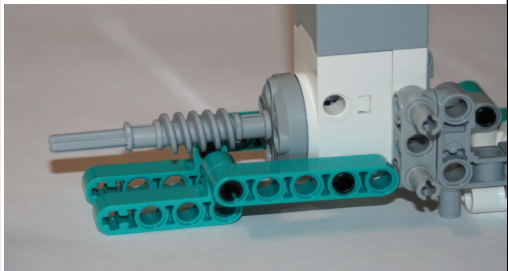


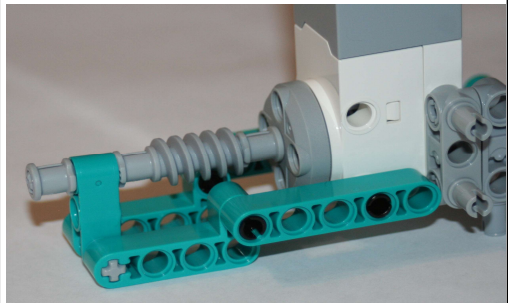



Étapes	Illustrations	Pièces nécessaires		Commentaires
1		1x		Insérer les deux pièces grises à l'une des extrémités de la pièce blanche.
		2x		
2		4x		
3		2x		
4		4x		
		2x		
5		2x		
		1x		
		2x		

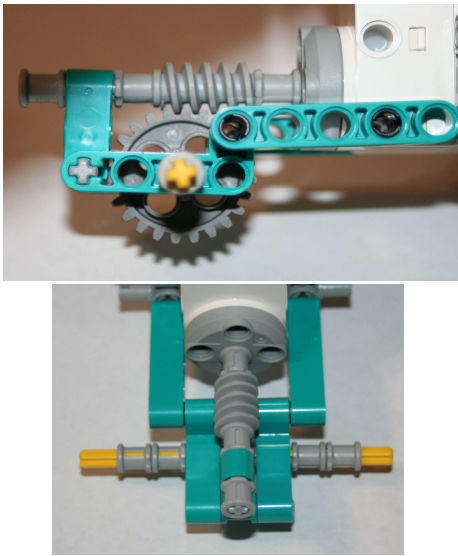
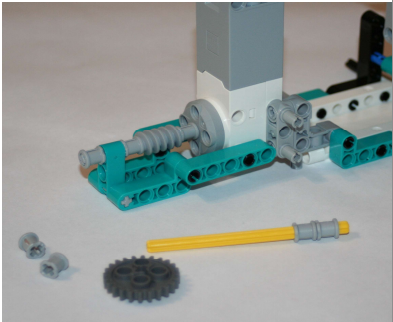
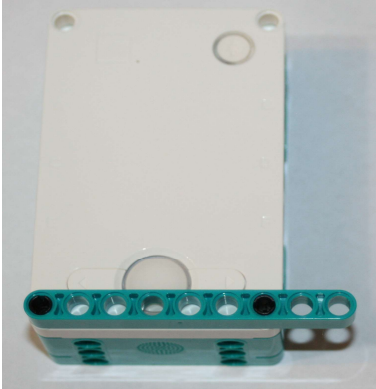



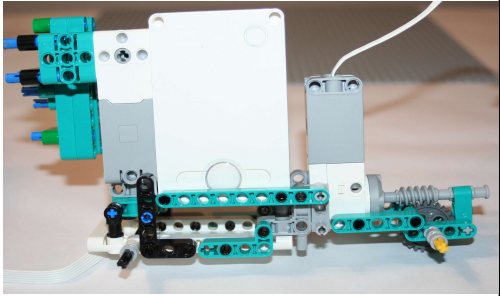
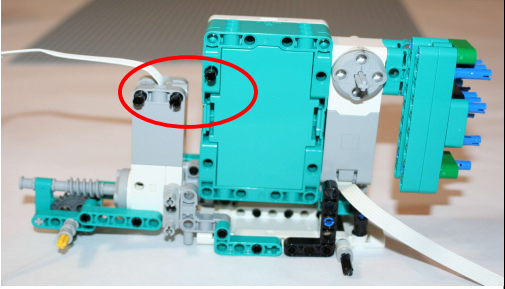

6		<div>2x </div> <div>2x </div> <div>2x </div>	
7		<div>2x </div> <div>1x </div> <div>2x </div>	
8	 	<div>1x </div> <div>1x </div> <div>1x </div> <div>1x </div>	

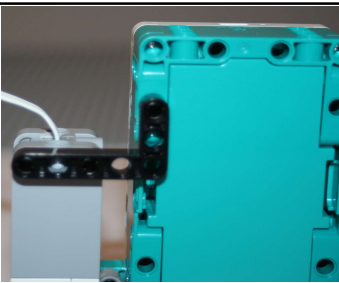

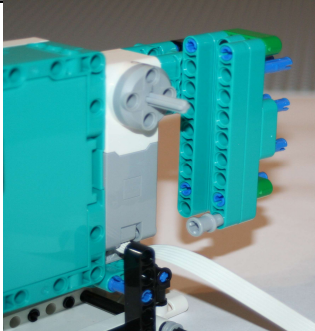

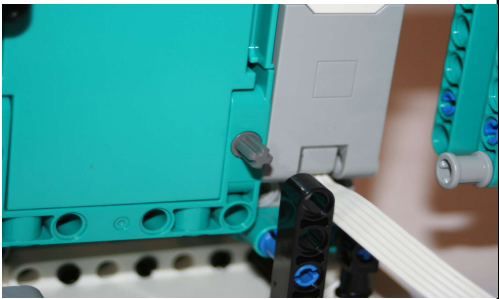




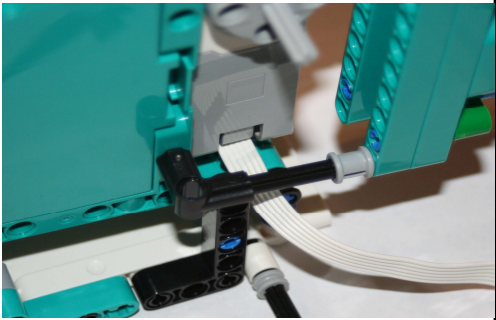

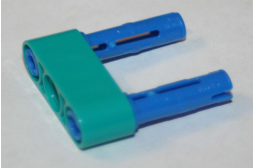


9			
10		4x 	
11		2x 	
12		4x 	

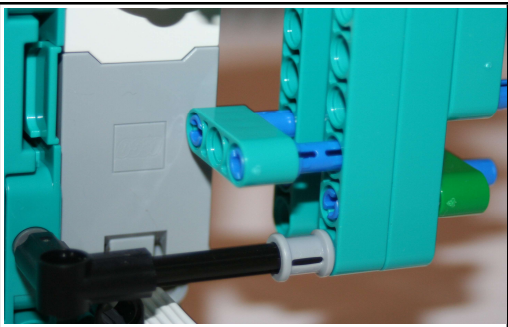
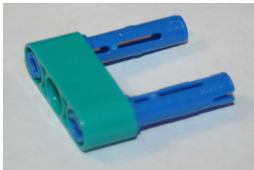
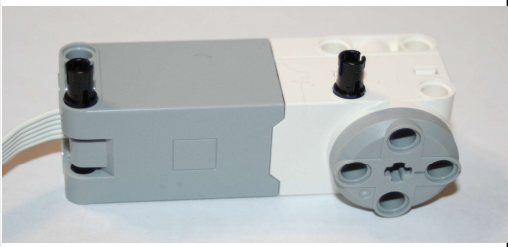


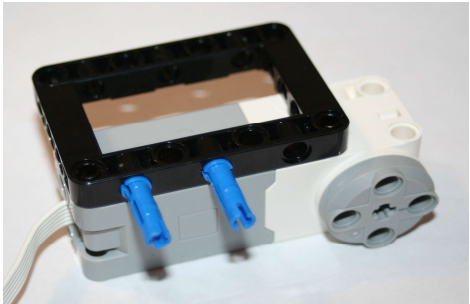
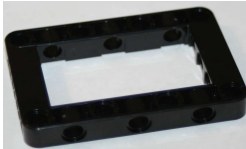

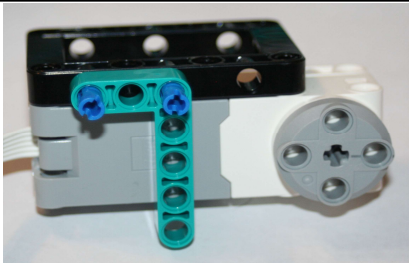
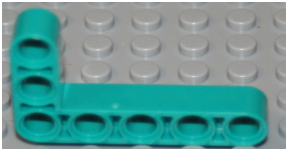
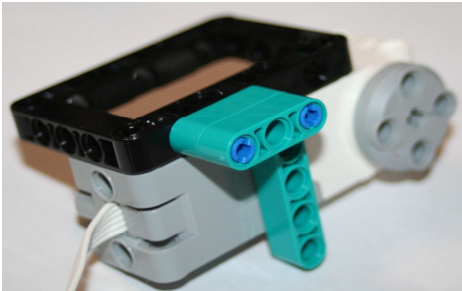

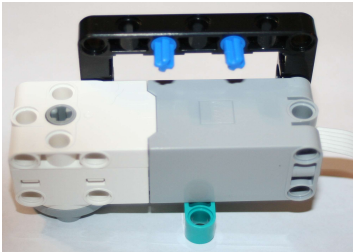

13		<div>4x </div> <div>2x </div>	
14		2x 	
15		<div>1x </div> <div>1x </div> <div>1x </div>	
16			Joindre les montages assemblés aux étapes 14 et 15 en plaçant celui de l'étape 15 au centre des montages de l'étape 14.
17		2x 	

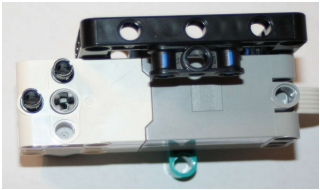


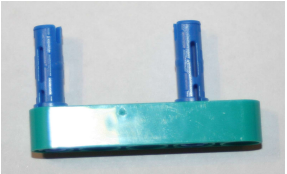



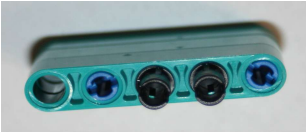


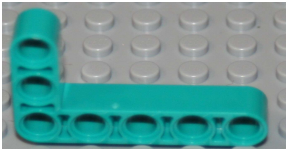

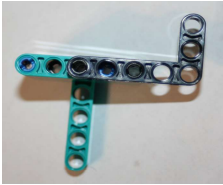


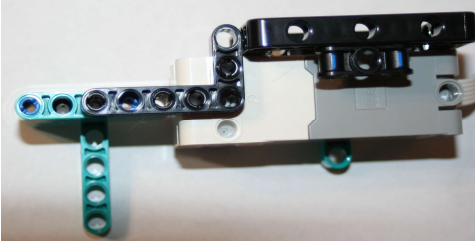

18		8x		
19		2x 1x	 	
20				
21		1x 2x	 	

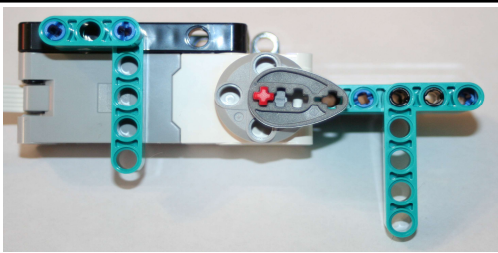


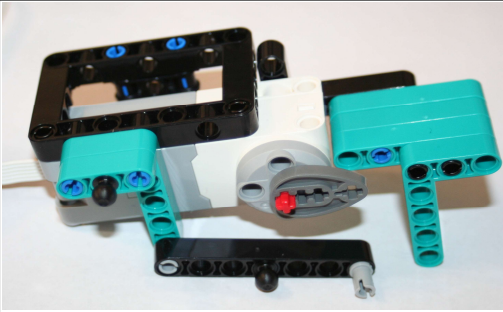



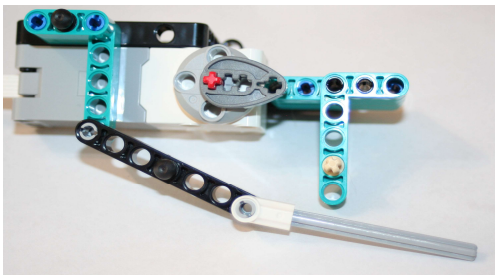


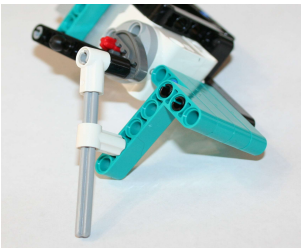


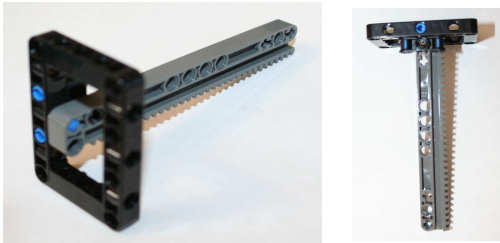
22			Insérer le moteur à l'arrière du robot.
23		2x 4x	 
24		1x	
25		2x	
26		1x 1x 2x	Vis sans fin  
27		1x 1x 1x	  

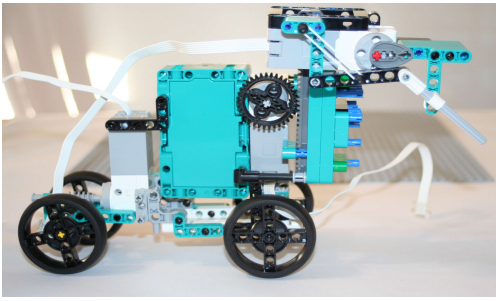
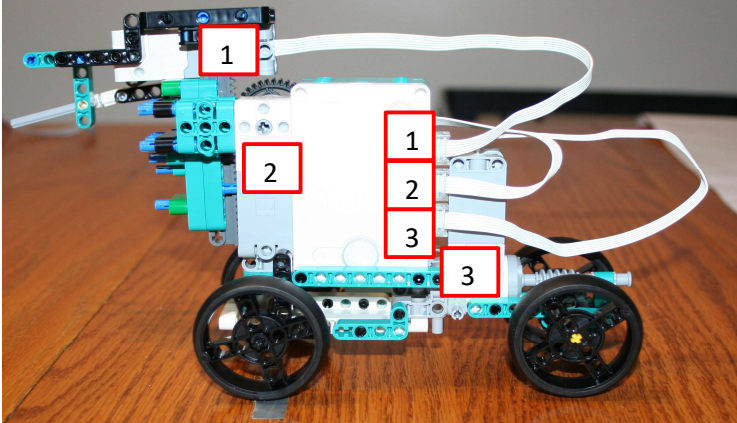
28			
29		<p>1x</p>  <p>1x</p>  <p>2x</p> 	
30			
31		<p>3x</p> 	

32		1x		
33		1x		
34		1x		
35		1x		
		1x		
36		1x		
37		1x		
		2x		

38		1x 	
39		1x  2x 	
40		1x  2x 	
41		1x 	
42		1x 	
43		2x 	

44		1x  2x 	
45	 	2x  3x 	
46	 	2x  1x 	
47	 	2x  1x 	
48		1x 	

49		1x 1x	 	
50		2x 2x 1x	  	
51		1x 1x	 	
52		1x		
53				
54				À insérer sur la pièce noire rectangulaire déjà installée sur le moteur. La crémaillère devrait s'insérer dans l'engrangement et le rail assemblé plus tôt.

55		<p>4x Roues</p> <p>1x Élastique</p>	
56		<p>Branchement des moteurs:</p> <p>Haut : Moteur 1</p> <p>Milieu : Moteur 2</p> <p>Bas : Moteur 3</p>	